Evaluation and Differentiation

A point

$$p(s) = \sum_{k=0}^{m-1} c_k b_k(s)$$

on a spline curve with knot sequence τ : $\tau_0, \ldots, \tau_{m+n}$ can be computed by repeatedly inserting *s* as a new knot until its multiplicity becomes *n*:

$$ilde{ au}_\ell < ilde{ au}_{\ell+1} = \cdots = ilde{ au}_{\ell+n} = s < ilde{ au}_{\ell+n+1} \implies p(s) = ilde{ au}_\ell\,,$$

where $ilde{ au}_\ell$ and $ilde{c}_k$ denote the modified knots and control points, respectively.



The refined control polygon \tilde{c} is tangent to the curve:

$$p'(s^-)=rac{n(ilde c_\ell- ilde c_{\ell-1})}{s- ilde \tau_\ell}, \quad p'(s^+)=rac{n(ilde c_{\ell+1}- ilde c_\ell)}{ ilde au_{\ell+n+1}-s}\,,$$

where the one-sided derivatives coincide if s is not a knot with multiplicity n of the original knot sequence τ (i.e., if at least one knot is inserted). In this case,

$$p'(s) = rac{n}{ ilde{ au}_{\ell+n+1} - ilde{ au}_{\ell}} \left(ilde{ extsf{c}}_{\ell+1} - ilde{ extsf{c}}_{\ell-1}
ight)$$

is an alternative formula for the tangent vector.

Bézier Form

The Bézier form of a spline curve parametrized by $p = \sum_{k=0}^{m-1} c_k b_k \in S_{\tau}^n$ is obtained by raising the multiplicity of each knot τ_k in the parameter interval $D_{\tau}^n = [\tau_n, \tau_m]$ to n. Then, for t in a nondegenerate parameter interval $[\tilde{\tau}_{\ell}, \tilde{\tau}_{\ell+1}] \subseteq D_{\tau}^n$ of the refined knot sequence $\tilde{\tau}$,

$$p(t) = \sum_{k=0}^n ilde{c}_{\ell-n+k} \, b_k^n(s), \quad s = rac{t- ilde{ au}_\ell}{ ilde{ au}_{\ell+1}- ilde{ au}_\ell} \in [0,1]\,,$$

where b_k^n are the Bernstein polynomials and \tilde{c}_k the control points with respect to $\tilde{\tau}$. Hence, up to linear reparametrization (which is immaterial for the shape of the curve), the spline segments have Bézier form.



As shown in the figure, every *n*th control point lies on the curve separating the Bézier segments. Thus, by converting to Bézier form, we can apply polynomial algorithms simultaneously on the different knot intervals.