## Evaluation and Differentiation

A point

$$
p(s)=\sum_{k=0}^{m-1} c_{k} b_{k}(s)
$$

on a spline curve with knot sequence $\tau: \tau_{0}, \ldots, \tau_{m+n}$ can be computed by repeatedly inserting $s$ as a new knot until its multiplicity becomes $n$ :

$$
\tilde{\tau}_{\ell}<\tilde{\tau}_{\ell+1}=\cdots=\tilde{\tau}_{\ell+n}=s<\tilde{\tau}_{\ell+n+1} \Longrightarrow p(s)=\tilde{c}_{\ell},
$$

where $\tilde{\tau}_{\ell}$ and $\tilde{c}_{k}$ denote the modified knots and control points, respectively.


The refined control polygon $\tilde{c}$ is tangent to the curve:

$$
p^{\prime}\left(s^{-}\right)=\frac{n\left(\tilde{c}_{\ell}-\tilde{c}_{\ell-1}\right)}{s-\tilde{\tau}_{\ell}}, \quad p^{\prime}\left(s^{+}\right)=\frac{n\left(\tilde{c}_{\ell+1}-\tilde{c}_{\ell}\right)}{\tilde{\tau}_{\ell+n+1}-s},
$$

where the one-sided derivatives coincide if $s$ is not a knot with multiplicity $n$ of the original knot sequence $\tau$ (i.e., if at least one knot is inserted). In this case,

$$
p^{\prime}(s)=\frac{n}{\tilde{\tau}_{\ell+n+1}-\tilde{\tau}_{\ell}}\left(\tilde{c}_{\ell+1}-\tilde{c}_{\ell-1}\right)
$$

is an alternative formula for the tangent vector.

## Bézier Form

The Bézier form of a spline curve parametrized by $p=\sum_{k=0}^{m-1} c_{k} b_{k} \in S_{\tau}^{n}$ is obtained by raising the multiplicity of each knot $\tau_{k}$ in the parameter interval $D_{\tau}^{n}=\left[\tau_{n}, \tau_{m}\right]$ to $n$. Then, for $t$ in a nondegenerate parameter interval $\left[\tilde{\tau}_{\ell}, \tilde{\tau}_{\ell+1}\right] \subseteq D_{\tau}^{n}$ of the refined knot sequence $\tilde{\tau}$,

$$
p(t)=\sum_{k=0}^{n} \tilde{c}_{\ell-n+k} b_{k}^{n}(s), \quad s=\frac{t-\tilde{\tau}_{\ell}}{\tilde{\tau}_{\ell+1}-\tilde{\tau}_{\ell}} \in[0,1]
$$

where $b_{k}^{n}$ are the Bernstein polynomials and $\tilde{c}_{k}$ the control points with respect to $\tilde{\tau}$. Hence, up to linear reparametrization (which is immaterial for the shape of the curve), the spline segments have Bézier form.


As shown in the figure, every $n$th control point lies on the curve separating the Bézier segments. Thus, by converting to Bézier form, we can apply polynomial algorithms simultaneously on the different knot intervals.

