

## Linear Elasticity

The displacement  $(u_1, u_2, u_3)$  caused by an elastic deformation minimizes the quadratic energy functional

$$\mathcal{Q}(u) = \frac{1}{2} \int_D \sum_{\nu, \nu'=1}^3 \varepsilon_{\nu, \nu'}(u) \sigma_{\nu, \nu'}(u) - \int_D \sum_{\nu=1}^3 f_{\nu} u_{\nu}, \quad u_{\nu} \in H_F^1(D),$$

where  $\varepsilon$  is the strain and  $\sigma$  is the stress tensor, defined by

$$2\varepsilon_{k,\ell} = \partial_k u_{\ell} + \partial_{\ell} u_k, \quad \sigma_{k,\ell} = \lambda \operatorname{trace} \varepsilon \delta_{k,\ell} + 2\mu \varepsilon_{k,\ell},$$

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Via the calculus of variations, the displacement can also be characterized by the Lamé–Navier boundary value problem

$$-\operatorname{div} \sigma(u) = f \text{ in } D, \quad u = 0 \text{ on } \Gamma, \quad \sigma(u)\eta = 0 \text{ on } \partial D \setminus \Gamma,$$

with  $\eta$  the outward unit normal of  $\partial D$ .