

A Systematic Cross-Comparison of Sequence Classifiers

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Abstract

In the CoNLL 2003 NER shared task, more than two thirds of the submitted systems used a feature-rich representation of the task. Most of them used the maximum entropy principle to combine the features together. Others used large margin linear classifiers, such as SVM and RRM. In this paper, we compare several common classifiers under exactly the same conditions, demonstrating that the ranking of systems in the shared task is due to feature selection and other causes and not due to inherent qualities of the algorithms, which should be ranked otherwise. We demonstrate that whole-sequence models generally outperform local models, and that large margin classifiers generally outperform maximum entropy-based classifiers.

1 Introduction

Recently, feature-rich classifiers became state-of-the-art in sequence labeling tasks, such as NP chunking, PoS tagging, and Named Entity Recognition. Such classifiers are able to use any property of tokens and their contexts, if the property can be represented in the form of real-valued (usually binary) feature functions. Since almost all local properties can be represented in such a way, this ability is very powerful.

Maximum-entropy-based models are currently the most prevalent type of feature-rich classifiers in sequence labeling tasks. Such models define a probability distribution over the set of labelings of a sentence, given the sentence. In this, such classifiers differ from the generative probabilistic classifiers, such as HMM-based Nymble (Bikel et al., 1999) and SCFG-based TEG (Rosenfeld et al., 2004), which model the joint probability of sequences and their labelings, and which can use only a very limited range of context features.

An alternative feature-rich approach is discriminative models, trained by maximizing the margin between correct and incorrect labelings. Recently, the maximal margin classifiers were adopted for multi-label classifi-

cation (Crammer, Singer, 2001) tasks and for structured classification tasks (Taskar, Guestrin, and Koller, 2003).

Another important difference among methods is their scope. The most often used methods are local, in the sense of modeling classification decisions separately for each sentence position. More recent methods model labeling of whole sequences.

In this work we compare the performance of four different classifiers within the same platform, using exactly the same set of features. MEMM (McCallum, Dayne Freitag, and Pereira, 2000; Chieu and Ng, 2002) and CRF (Lafferty, McCallum, and Pereira, 2001; McCallum and Li, 2003) are a local and a whole-sequence maximum entropy based classifiers. RRM (regularized Winnow) (Zhang and Johnson, 2003) and MIRA (McDonald, Crammer and Pereira, 2004) are a local and a whole-sequence maximal margin classifiers. We test the effects of different training sizes, different choice of parameters, and different feature sets upon the algorithms' performance.

Our experiments indicate that whole-sequence models outperform local models, as expected. Also, although the effect is less pronounced, maximal margin models generally outperform maximum entropy based models. We will present our experiments and their results.

2 Experimental Setup

The goal of this work is to compare the four sequence labeling algorithms in several different dimensions: absolute performance, dependence upon the corpus, dependence upon the training set size and the feature set, and dependence upon the hyperparameters.

2.1 Datasets

For our experiments we used four datasets: CoNLL-E, the English CoNLL 2003 shared task dataset, CoNLL-D, the German CoNLL 2003 shared task dataset, the MUC-7 dataset (Chinchor, 1998), and the proprietary CLF dataset (Rosenfeld et al., 2004). For the experiments with smaller training sizes, we cut training corpora into chunks of 10K, 20K, 40K, 80K, and 160K tokens. In the following sections, the datasets are denoted $\langle \text{Corpus} \rangle_{\langle \text{Size} \rangle}$, e.g. "CoNLL-E_10K".

2.2 Feature Sets

There are many properties of tokens and their contexts that can be used in a NER system. We experiment with the following properties, ordered according to the difficulty of obtaining them (all of the properties except the last two apply to tokens inside a small window around the given position):

- A. The exact character strings of tokens.
- B. Lowercase character strings of tokens.
- C. Simple properties of characters inside tokens, such as capitalization, letters vs digits, punctuation, etc.
- B×C. Products of features from “B” and “C” for adjacent tokens inside the window.
- D. Suffixes and prefixes of tokens with lengths between 2 to 4 characters.
- E. Presence of tokens in local and global dictionaries, which contain words that were classified as certain entities someplace before – either anywhere (for global dictionaries), or in the current document (for local dictionaries).
- F. PoS tags of tokens.
- G. Stems of tokens.
- H. Presence of tokens in small manually prepared lists of semantic terms – such as months, days of the week, geographical features, company suffixes, etc.
- I. Presence of tokens inside gazetteers, which are huge lists of known entities.

The PoS tags are available only for the two CoNLL datasets, and the stems are available only for the CoNLL-D dataset. Both are automatically generated and thus contain many errors. The gazetteers and lists of semantic terms are available for all datasets except CoNLL-D.

We tested the following feature sets:

set0: checks properties A, B, C at the current and the previous token.

set1: A, B, C, B×C in a window [-2...0].

set2: A, B, C, B×C in a window [-2...+2].

set2x: Same as set2, but only properties

appearing > 3 times are used.

set3: A, B, C, B×C in a window [-2...+2], D at the current token.

set4: A, B, C, B×C in a window [-2...+2], D at the current token, E.

set5: A, B, C, B×C, F, G in a window [-2...+2], D at the current token, E.

set6: set4 or set5, H

set7: set4 or set5, H, I

2.3 Hyperparameters

The MaxEntropy-based algorithms, MEMM and CRF, have similar hyperparameters, which define the priors for training the models. We experimented with two different priors – Laplacian (double exponential) $\Pr_{\text{LAP}}(\boldsymbol{\lambda}) = \alpha \prod_i |\lambda_i|$ and Gaussian $\Pr_{\text{GAU}}(\boldsymbol{\lambda}) = (\prod_i \lambda_i^2) / (2\sigma^2)$. Each prior depends upon a single hyperparameter specifying the “strength” of the prior. Note, that $\nabla \Pr_{\text{LAP}}(\boldsymbol{\lambda})$ has discontinuities at zeroes of λ_i . Because of that, a special consideration must be given to the cases when λ_i approaches or is at zero. Namely,

- (1) if λ_i tries to change sign, set $\lambda_i := 0$, and allow it to change sign only on the next iteration, and
- (2) if $\lambda_i = 0$, and $\left| \frac{\partial}{\partial \lambda_i} L_T(\boldsymbol{\lambda}) \right| < \alpha$, do not allow λ_i to change, because it will immediately be driven back toward zero.

In some of the previous work (e.g., Peng and McCallum, 1997), the Laplacian prior was reported to produce much worse performance than the Gaussian prior. Our experiments show them to perform similarly. The likely reason for this difference is the different way of handling the zero discontinuities.

RRM algorithm has three hyperparameters – the prior μ , the regularization parameter c , and the learning rate η .

MIRA algorithm has two hyperparameters – the regularization parameter c and the number K of incorrect labelings that are taken into account at each step.

RRM		MUC7_40K_set7			CLF_80K_set2			CoNLL-E_160K_set2x		
		c=0.001	c=0.01	c=0.1	c=0.001	c=0.01	c=0.1	c=0.001	c=0.01	c=0.1
$\mu=0.01$	$\eta=0.001$	48.722	48.722	48.65	49.229	49.229	49.244	84.965	84.965	84.965
	$\eta=0.01$	63.22	63.207	62.915	64	64.04	63.71	90.246	90.238	90.212
	$\eta=0.1$	61.824	62.128	63.678	58.088	58.628	61.548	89.761	89.776	89.904
$\mu=0.1$	$\eta=0.001$	60.262	60.249	60.221	59.943	59.943	59.943	89.556	89.556	89.573
	$\eta=0.01$	65.529	65.547	65.516	64.913	64.913	64.811	91.175	91.175	91.15
	$\eta=0.1$	60.415	60.958	63.12	55.04	55.677	60.161	30.741	30.741	56.445
$\mu=1$	$\eta=0.001$	66.231	66.231	66.174	65.408	65.408	65.408	91.056	91.056	91.056
	$\eta=0.01$	62.622	62.579	62.825	59.197	59.311	59.687	90.286	90.317	90.351
	$\eta=0.1$	2.922	2.922	8.725	0	0	1.909	0	0	0

Table 1. RRM results with different hyperparameter settings.

CRF	CLF			CoNLL-D			MUC7	CoNLL-E
	20K_set7	40K_set7	80K_set7	40Kset2x	80Kset2x	160Kset2x	80K_set2	80K_set2
GAU $\sigma = 1$	76.646	78.085	80.64	29.851	35.516	39.248	80.756	69.247
GAU $\sigma = 3$	75.222	77.553	79.821	28.53	35.771	38.254	80.355	69.693
GAU $\sigma = 5$	75.031	77.525	79.285	29.901	35.541	38.671	79.853	69.377
GAU $\sigma = 7$	74.463	77.633	79.454	30.975	36.517	38.748	79.585	69.341
GAU $\sigma = 10$	74.352	77.05	77.705	29.269	36.091	38.833	80.625	68.974
LAP $\alpha=0.01$	73.773	77.446	79.071	29.085	35.811	38.947	79.738	69.388
LAP $\alpha=0.03$	75.023	77.242	78.81	31.082	34.097	38.454	79.044	69.583
LAP $\alpha=0.05$	76.314	77.037	79.404	30.303	35.494	39.248	79.952	69.161
LAP $\alpha=0.07$	74.666	76.329	80.841	30.675	34.53	38.882	79.724	68.806
LAP $\alpha=0.1$	74.985	77.655	80.095	31.161	35.187	39.234	79.185	68.955

Table 2. CRF results with different hyperparameter settings.

MEMM	CLF			CoNLL-D			MUC7	CoNLL-E
	20K_set7	40K_set7	80K_set7	40Kset2x	80Kset2x	160Kset2x	80K_set2	80K_set2
GAU $\sigma = 1$	75.334	78.872	79.364	30.406	35.013	40.164	78.773	67.537
GAU $\sigma = 3$	74.099	75.693	77.278	28.484	35.33	40.005	77.295	67.401
GAU $\sigma = 5$	73.959	74.685	77.316	28.526	35.043	39.799	77.489	67.87
GAU $\sigma = 7$	73.411	74.505	77.563	28.636	34.63	38.531	77.255	67.897
GAU $\sigma = 10$	73.351	74.398	77.379	28.488	33.955	37.83	77.094	68.043
LAP $\alpha=0.01$	71.225	74.04	75.721	28.316	34.329	40.074	78.312	67.871
LAP $\alpha=0.03$	72.603	72.967	76.54	29.086	35.159	38.621	77.385	67.401
LAP $\alpha=0.05$	71.921	75.523	75.37	30.425	33.942	39.984	78.262	67.908
LAP $\alpha=0.07$	72.019	74.486	77.197	30.118	35.25	39.195	76.646	67.833
LAP $\alpha=0.1$	72.695	75.311	76.335	30.315	33.487	40.861	78.141	67.421

Table 3. MEMM results with different hyperparameter settings.

MIRA	CLF_20K_set7				CoNLL-D_40K_set2x			
	K=1	K=3	K=5	K=10	K=1	K=3	K=5	K=10
$c=1$	73.395	73.063	73.894	73.567	25.816	26.473	26.611	27.003
$c=10$	73.471	72.839	73.906	74.029	26.968	27.699	26.477	26.127
$c=20$	74.015	73.013	73.924	74.092	24.619	23.209	23.906	25.163
$c=50$	74.617	72.824	74.969	73.791	19.533	18.929	17.952	18.934
	CoNLL-E_80_set2				MUC7_40_set2x			
$c=1$	83.402	83.286	83.302	83.34	64.269	63.464	64.151	63.878
$c=10$	83.131	82.459	82.375	82.462	63.935	64.31	64.824	64.243
$c=20$	82.167	82.039	81.592	81.795	64.105	62.941	62.857	63.313
$c=50$	77.909	77.097	76.585	77.719	59.759	59.542	58.964	59.987

Table 4. MIRA results with different hyperparameter settings.

3 Experimental Results

It is not possible to test every possible combination of algorithm, dataset and hyperparameter. Therefore, we tried to do a meaningful series of experiments, which would together highlight the different aspects of the algorithms.

All of the results are presented as final microaveraged F1 scores.

3.1 Influence of the hyperparameters

In the first series of experiments we evaluated the dependence of the performance of the classifiers upon their hyperparameters. All of the algorithms showed moderate and rather irregular dependence upon their hyperparameters. Because of the irregularity, fine-tuning of parameters on a held-out set has little meaning. Instead, we chose a single good overall set of values and used them for all subsequent experiments.

A selection of the RRM results is shown in the Table 1. As can be seen, setting $\mu = 0.1$, $c = 0.01$ and $\eta = 0.01$

gives reasonably close to optimal performance on all datasets. All subsequent experiments were done with those hyperparameter values.

Likewise, the ME-based algorithms have no single best set of hyperparameter values, but have close enough near-optimal values. A selection of MEMM and CRF results is shown in the Table 2 and Table 3. For subsequent experiments we use CRF with Laplacian prior with $\alpha = 0.07$ and MEMM with Gaussian prior with $\sigma = 1$.

MIRA results are shown in the Table 4. For the subsequent experiments we use $K = 5$ and $c = 10$.

In this series of experiments we evaluated the performance of the algorithms using progressively bigger training datasets: 10K, 20K, 40K, 80K and 160K tokens. The results are summarized in the Fig.1. As expected, the algorithms exhibit very similar training size vs. performance behavior.

3.2 Influence of the feature sets

In this series of experiments we trained the models with all available training data, but using different feature sets. The results are summarized in the Table 5. The results were tested for statistical significance using the McNemar test. All the performance differences between the successive feature sets are significant at least

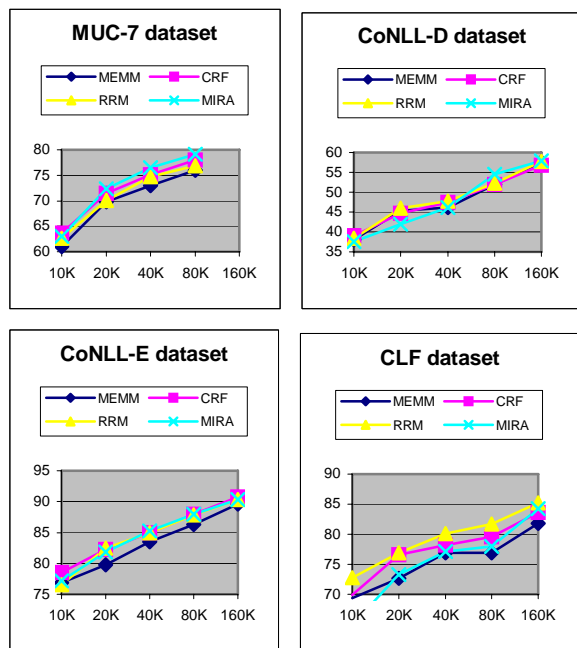


Fig 1. Performance of the algorithms on datasets of different sizes.

at the level $p=0.05$, except for the difference between set4 and set5 in CoNLL-E dataset for all models, and the differences between set0, set1, and set2 in CoNLL-E

and MUC7 datasets for CRF and MIRA models. Those are statistically insignificant. The differences between the performance of different models that use same feature sets are also mostly significant. Exceptions are the numbers preceded by a tilde “~”. Those numbers are not significantly different from the best results in their corresponding rows.

As can be seen, MEMM performs worst, as all of the other models generally outperform it. MIRA and CRF perform comparably with all feature sets and document collections, while RRM is better on CoNLL-D, worse on MUC-7, and similar to them on CoNLL-E.

Comparing maximal-margin-based vs. maximum-entropy-based models, we note that RRM always wins over MEMM, while CRF and MIRA perform very close to each other. The possible conclusion is that maximal margin classifiers should in general perform better, but the effect is masked in case of MIRA by its being only an approximation of a true large margin classifier.

Comparing whole-sequence vs. local models, we see that CRF always wins over MEMM, but MIRA sometimes loses to RRM. However, it is interesting to note that both CRF and MIRA win over local models by a large margin on feature sets 0 and 1, which are distinguished from the set 2 by absence of “forward-looking” features. Indeed, using “forward-looking” features produces little or no improvement for MIRA and CRF, but very big improvement for local models, probably because such features help to alleviate the *label bias problem* (Lafferty et al., 2001). The possible conclusion is that the whole-sequence classifiers should in general perform better, but the effect becomes less pronounced as bigger feature sets are used, within larger window around the current token.

Finally, we should note the very good performance of the RRM. It is not only one of the best-performing, but also fastest to train and simplest to implement.

4 Conclusions

We have presented a set of experiments comparing four common state-of-the-art feature-rich sequence classifiers inside a single system, using completely identical feature sets. The experiments show that classifiers modeling labeling decisions for whole sequences should outperform local models, so the comparatively poor performance of CRF in the CoNLL 2003 NER task (McCallum and Li, 2003) is due to suboptimal feature selection and not to any inherent flaw in the algorithm itself.

	MUC7				CoNLL-D				CoNLL-E			
	CRF	MEMM	RRM	MIRA	CRF	MEMM	RRM	MIRA	CRF	MEMM	RRM	MIRA
set0	75.75	66.58	62.206	73.16	48.99	43.36	40.11	~48.53	87.38	82.28	76.89	86.01
set1	75.54	67.08	68.405	73.98	50.67	49.16	48.05	~50.31	87.36	82.52	81.79	86.01
set2	75.29	74.00	74.75	74.50	~52.13	52.01	51.54	52.51	86.89	87.09	87.76	~87.48
set3	76.91	76.33	~76.79	~76.90	60.17	59.53	61.10	60.32	~88.93	88.71	89.11	~89.05
set4	78.34	77.89	77.83	~78.12	62.79	63.58	65.80	64.49	90.04	90.05	90.72	~90.65
set5					65.65	65.32	67.81	65.33	90.14	90.12	~90.56	90.62
set6	~78.97	78.44	78.02	79.15					~90.57	~90.49	~90.98	90.99
set7	81.79	80.92	81.06	~81.46					~91.41	90.88	~91.78	91.82

Table 5. Performance of the algorithms using different feature sets

We also demonstrated that Large Margin systems generally outperform the Maximum Entropy models. However, building full-scale Maximal Margin models for whole sequences, such as M³ Networks (Taskar, Guestrin, and Koller, 2003), is very time-consuming with currently known methods and the training appears much slower than training of corresponding CRF. Approximations such as MIRA can be built instead, which perform at more or less the level of CRF.

In addition, we demonstrated that the Laplacian prior performs just as well and sometimes better than Gaussian prior, contrary to the results of some of the previous researches.

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